

Amplifier Built-in Compact Photoelectric Sensor

CX-400 SERIES Ver.2



Global Standard



Upgraded to Increase Usability

Achieving low power consumption and high noise-resistance The basic types are added in lineup

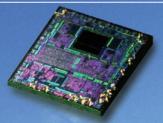
2024.8

The global standard CX-400 series Sensors that are environmentally and user friendly.

The various lineup covers through the inclusion of a newly developed custom integrated circuit. The **CX-400** series achieves a significantly higher reliability in the same package than previous models.



Providing stable detection with low power consumption Includes an analog CMOS processor ASIC



The Three Keywords Expressing CX-400 Series' World-Class Performance

Strong

Demonstrating stable detection, even in harsh environments

Resistant to oil and coolant liquids

The lens material is made of a strong acrylic that resists the harmful effects of coolants. These sensors can be used with confidence even around metal processing machine that disperse oil mists. The protection mechanism also conforms to IP67 (IEC).



CX-410/420/490

Test Oil	JIS Standard	Product Name
Lubricant	-	Velocity Oil No. 3
Water-insoluble	2-5	Daphnecut AS-30D
cutting oil	2-11	Yushiron Oil No.2ac (Note)
Water-soluble	W1-1	Yushiron Lubic HWC68 (Note)
cutting oil	W2-1	Yushiroken S50N (Note)
1.000 hours: Imm	ersion (depth 0 m): Insulation resistance 20 MO/250 \

 1,000 hours; Immersion (depth 0 m); Insulation resistance 20 MΩ/250 \ Note: Yushiron and Yushiroken are registered trademarks of Yushiro Chemical Industry Co., Ltd.

Strongly ethanol resistant

A strong, ethanol resistant polycarbonate was used for the front and display covers. Safe even for installing near food processing machinery that disperses ethanol based detergents. The protection mechanism also conforms to IP67 (IEC).

Caution: Set the CX-48 so that cleaning liquid will not get on to the attached reflector.

Strong construction to resist water and dust

Achieving the IP67 protection rating (IEC), the **CX-400** series can be used safely in environments where water and dust are present. Caution: The sensor may detect water if water splashes on the unit during detection operation.



CX-44□/48□







Upgrade

Reducing environmental burdens further

Up to 60% less power consumption

The **CX-400** series achieves reductions in power consumption of up to 60%, averaging 44% reduction when upgrading due to its unique design. These sensors reduce carbon emissions and contribute to environmental friendliness.



Contributing to reduced carbon dioxide emissions

Electricity consumed by the **CX-400** series has been reduced on average 10.5 mA. Calculating 8 hours/day, 260 days (operating 5 days/week) for a total of 2,080 hours/year leads to:

The **CX-400** contributes

Approx. 84.6 t annually in carbon dioxide reductions to the world

Upgrade 🦯

Stronger noise resistance

Stronger inverter countermeasures

The **CX-400** has a high noise resistance then its previons model. By incorporating an inverter countermeasure circuit that appropriately shifts with peak wavelength, the sensor now resists high-frequency noise from high-voltage inverter motors and inverter lights more effectively.

Upgrade 🍼

Stronger output short-circuit resistance

Stronger inverse wiring connection protection

Strengthening the output circuit inverse polarity protection prevents sensor damage caused by mistaken output or power supply wiring.



High performance for many applications



The **CX-400** series is capable of stably detecting a minute difference of 0.4 mm 0.016 in (the thickness of a business card) or 10 μ m 0.394 mil ultra-thin film, thanks to its unique optics and specialized design of electronic circuits. Bright red beam spot is useful when confirming a detection position.

Save

Thoroughly eliminating unnecessary waste, reducing many environmental burdens



The **CX-400** series has three different cable length types and uses very simple packaging to reduce waste. The bag is made of polyethylene and does not emit toxic gasses.



Built-in polarizing filters ensure stable sensing even on a mirror surface object.

Two sensors can be mounted close together

 CX-49□/48□

Up to two sensors can be mounted closely by the automatic interference prevention function.

For transparent object sensing

Sensing range

CX-482: 0.1 to 2 m 0.328 to 6.562 ft **CX-483**: 50 to 1,000 mm 1.969 to 39.37 in **CX-481**: 50 to 500 mm 1.969 to 19.685 in



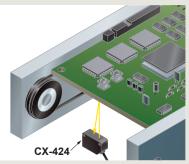
Reduction of volume adjustment labor CX-42□

Because these sensors possess many variations depending on the sensing range, they enable you to make optimal volume adjustment easily.

Two sensors can be mounted close together CX-42

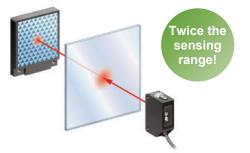
Up to two sensors can be mounted closely by the automatic interference prevention function.

Passage confirmation on substrate



Transparent object sensing type sensor CX-48

Our unique optical system and transparent object sensing circuit provide stable sensing of thinner transparent objects than the conventional models.



Transparent objects detectable with CX-48 (Typical examples)

Sensing object	Sensing object size	ze (mm <mark>in</mark>)
Glass sheet	□50 □1.969	t=0.7 t=0.028
Cylindrical glass	ø50 ø1.969 l =50 l =1.969	t=1.3 t=0.051
Acrylic board	□50 □1.969	t=1.0 t=0.039
Styrol (Floppy case)	□50 □1.969	t=0.9 t=0.035
Food wrapping film	□50 □1.969	t=10 µm t=0.394 mil
Cigarette case film	□50 □1.969	t=20 µm t=0.787 mil
Vinyl bag	□50 □1.969	t=30 µm t=1.181 mil
Pet bottle (500ml)	ø66 ø2.598	

Reflector setting range CX-481: 300 to 500 mm 11.811 to 19.685 in CX-482: 1 to 2 m 3.281 to 6.562 ft

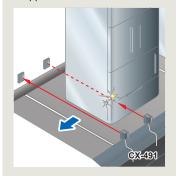
CX-483: 500 to 1,000 mm 19.685 to 39.370 in

[with the RF-230 reflector at the optimum condition (Note)] Each object should pass across the beam at the center between the sensor and the reflector.

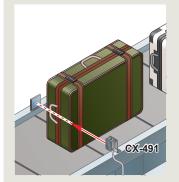
- ℓ : Length of cylindrical glasses
- t : Thickness of sensing object
- Note: The optimum condition is defined as the condition in which the sensitivity level is set such that the stability indicator just lights up when the object is absent.

Applications

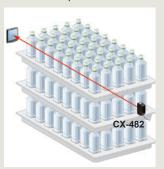
 Detecting glossy electric appliances



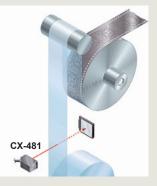
Passage confirmation of object on a conveyor belt



Detecting plastic bottles stacked on pallets



Detecting TAB protective transparent film



Adjustable range reflective type



Spot diameter ø9 mm ø0.354 in approx.

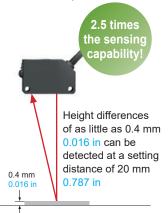
20 to 50 mm 0.787 to 1.969 in Spot diameter ø2 mm ø0.079 in approx.

*At the maximum distance

High precision type CX-441/444

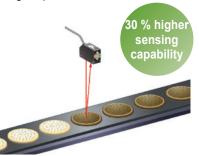
Can sense height differences as small as 0.4 mm 0.016 in, with hysteresis of 2 % or less

An advanced optical system provides sensing performance that is approx. 2.5 times than conventional models. Even ultra-small differences of 0.4 mm 0.016 in can be detected accurately.



Hardly affected by colors

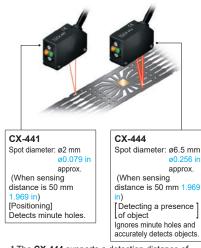
Both black and white objects can be sensed at the same distances. No adjuster control is needed, even when products of different colors are moving along the production line.



The difference in sensing range 1% or less between non-glossy white paper with a setting distance of 50 mm 1.969 in and non-glossy gray paper with a brightness level of 5.

Select from 2 spot diameters as per application

We offer small spot type for detecting minute objects and large spot type capable of sensing objects covered with holes and grooves.



* The CX-444 supports a detection distance of up to 100 mm 3.937 in.

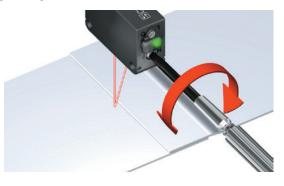
The bright spot makes beam axis alignment easy CX-44□

These sensors have a high luminance red spot that provides bright visibility. The sensing position can be checked at a glance. Because the CX-441 sensor has a small spot beam, at approx. ø2 mm ø0.079 in, even the minutest object can be accurately detected



Can be used for sensing minute differences CX-44□

Equipped with a multirotation adjuster so that even challenging range settings can be handled with ease.



Equipped with automatic interference prevention function CX-44

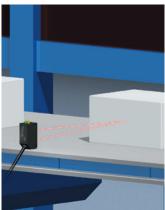
The automatic interference prevention function prevents mutual interference.

BGS / FGS functions make even the most challenging settings possible! CX-440

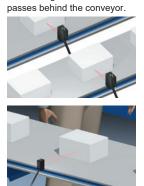
The BGS function is best suited for the following case

BGS

Background not present When object and background are separated

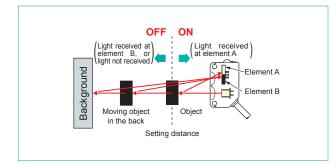


Not affected if the background color changes or someone



BGS (Background suppression) function

The sensor judges that an object is present when light is received at position A of the light-receiving element (2-segment element). This is useful if the object and background are far apart. The distance adjustment method is the same as the conventional adjustment method for adjustable range reflective type sensors.

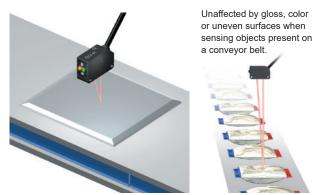


The FGS function is best suited for the following case



Background present

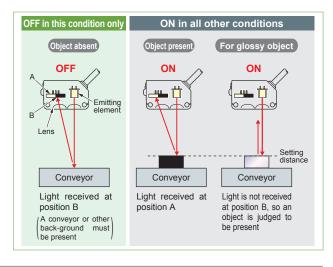
When object and background are close together When the object is glossy or uneven



Note: Please use the FGS function together with a conveyor or other background unit.

FGS (Foreground suppression) function

The sensor judges that an object is present when no light is received at position B of the light-receiving element (2-segment element). Accordingly, even objects that are glossy can be sensed. This is useful if the object and background are close together, or if the object being sensed is glossy.



Applications

Small tablet detection

Detects minute objects unaffected by glossy background objects. Uses FGS function.



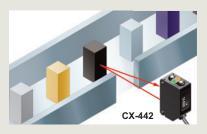
Thin biscuit detection

Stable sensing even for thin objects. Uses FGS function.



Passage confirmation

Not affected by color variations in objects and background objects. Uses BGS function.



ORDER GUIDE

-			Model No	. (Note 1)	Output	Emitting
Туре	Appearance	Sensing range	NPN output	PNP output	operation	element
E		10 m 32.808 ft	CX-411	CX-411-P		Red LED
Thru-beam sensing		15 m 49.213 ft	CX-412	CX-412-P		Infrared
Long		30 m 98.425 ft	CX-413	CX-413-P		LED
With polarizing filters		3 m 9.843 ft (Note 2)	CX-491	CX-491-P		
sensing		5 m 16.404 ft (Note 2)	CX-493	СХ-493-Р		Red LED
lect		50 to 500 mm 1.969 to 19.685 in (Note 2)	CX-481	CX-481-P	Switchable	
Retroref For transparent object sensing		50 to 1,000mm 1.969 to 39.37 in (Note 2)	CX-483	СХ-483-Р	either Light-ON or Dark-ON	Infrared LED
For obje		0.1 to 2 m 0.328 to 6.562 ft (Note 2)	CX-482	CX-482-P		
		100 mm 3.937 in	CX-424	СХ-424-Р		
eflective		300 mm 11.811 in	CX-421	CX-421-P		Infrared LED
Diffuse reflective		800 mm 31.496 in	CX-422	СХ-422-Р		
Larrow-view		70 to 300 mm 2.756 to 11.811 in	CX-423	СХ-423-Р		Red LED
ective Small spot		2 to 50 mm 0.079 to 1.969 in Adjustable range: 20 to 50 mm 0.787 to 1.969 in	CX-441	СХ-441-Р		
nge refle		2 to 50 mm 0.079 to 1.969 in (Distance setting: 50 mm 1.969 in)	CX 444	CY 444 F	Switchable either	Ded I CD
Adjustable range reflective		15 to 100 mm 0.591 to 3.937 in (Distance setting: 100 mm 3.937 in) Adjustable range: 20 to 100 mm 0.787 to 3.937 in	CX-444	СХ-444-Р	Detection-ON or Detection-OFF	Red LED
Adjus		20 to 300 mm 0.787 to 11.811 in Adjustable range: 40 to 300 mm 1.575 to 11.811 in	CX-442	CX-442-P		

NOTE: Mounting bracket is not supplied with the sensor. Please select from the range of optional sensor mounting brackets.

Notes: 1) The model No. with "E" shown on the label affixed to the thru-beam type sensor is the emitter, "D" shown on the label is the receiver.
2) The sensing range of the retroreflective type sensor is specified for the RF-230 reflector. The sensing range represents the actual sensing range of the sensor. The sensing ranges itemized in "A" of the table below may vary depending on the shape of sensing object. Be sure to check the operation with the actual sensing object.

Sensing		CX-491□	CX-493□	CX-481□	CX-483□	CX-482□
Sensing object	А	0 to 3 m 0 to 9.843 ft			50 to 1,000 mm 1.969 to 39.37 in	0.1 to 2 m 0.328 to 6.562 ft
Setting range of the reflector: B			0.1 to 5 m 0.328 to 16.404 ft		100 to 1,000 mm 3.937 to 39.37 in	0.8 to 2 m 2.625 to 6.562 ft
Sensor Reflector						

Desimation	Mode	el No.		Sensin	g range	Min. sens	sing object	
Designation	Slit mask	Sensor	Slit size	Slit on one side	Slit on both sides	Slit on one side	Slit on both sides	
		CX-411□		400 mm 15.748 in	20 mm 0.787 in			
	OS-CX-05	CX-412□	ø0.5 mm ø0.020 in	600 mm 23.622 in	30 mm 1.181 in	ø12 mm ø0.472 in	ø0.5 mm ø0.020 in	
		CX-413□		1,200 mm 47.242 in	60 mm 2.362 in			
Round slit mask		CX-411□		900 mm 35.433 in	100 mm 3.937 in		ø1 mm ø0.039 in	
For thru- beam type	OS-CX-1	CX-412□	ø1 mm ø0.039 in	1.35 m 4.429 ft	150 mm 5.906 in	ø12 mm ø0.472 in	ø1.5 mm ø0.059 in	
sensor only		CX-413□		2.7 m 8.857 ft	300 mm 11.811 in		Ø1.5 mm Ø0.059 in	
		CX-411□		2 m 6.562 ft	400 mm 15.748 in		ø2 mm ø0.079 in	
	OS-CX-2 CX-412	CX-412□	ø2 mm ø0.079 in	3 m 9.843 ft	600 mm 23.622 in	ø12 mm ø0.472 in	ø3 mm ø0.118 in	
		CX-413□		6 m 19.685 ft	1,200 mm 47.242 in		03 1111 00. 118 11	
		CX-411□		2 m 6.562 ft	400 mm 15.748 in		0.5×6 mm 0.020×0.236 in	
	OS-CX-05×6	OS-CX-05×6 CX-412□ 0.5×6 mm	0.5×6 mm 0.020×0.236 in	3 m 9.843 ft	600 mm 23.622 in	ø12 mm ø0.472 in		
		CX-413□		6 m 19.685 ft	1,200 mm 47.242 in			
Rectangular slit mask		CX-411□		3 m 9.843 ft	1 m 3.281 ft			
For thru-		CX-412□	1×6 mm 0.039×0.236 in	4.5 m 14.764 ft	1.5 m 4.921 ft	ø12 mm ø0.472 in	1×6 mm 0.039×0.236 in	
beam type sensor only		CX-413□		9 m 29.528 ft	3 m 9.843 ft			
		CX-411□		5 m 16.404 ft	2 m 6.562 ft			
	OS-CX-2×6	CX-412□	2×6 mm 0.079×0.236 in	7.5 m 24.606 ft	3 m 9.843 ft	ø12 mm ø0.472 in	2×6 mm 0.079×0.236 in	
		CX-413□		15 m 49.213 ft	6 m 19.685 ft			

Designation	Model No. (Note 1)	Direction of thru-beam axis	Color of metal	Sensing range	Min. sensing object
Interference prevention filter (For CX-411 □ only)	PF-CX4-H	Horizontal	Light brown	5 m 16.404 ft	ø12 mm ø0.472 in
A set of emitter filter and receiver filter	PF-CX4-V	Vertical	Silver	(Note 2)	(Note 2)

Notes: 1) The model No. is not shown on the interference prevention filters. Take care when mounting them on the sensors. 2) Value when attached on both sides.

Round slit mask

- OS-CX-🗆
- Fitted on the front face of the sensor with onetouch.



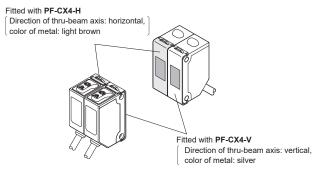
Interference prevention filter

- · PF-CX4-H
- (Direction of thru-beam axis: Horizontal, Color of metal: Light brown) **PF-CX4-V**

(Direction of thru-beam axis: Vertical, Color of metal: Silver)

Fitted on the front face of the sensor with one-touch.

By mounting the interference prevention filters **PF-CX4-** $_{\Box}$, up to two sets of the **CX-411** $_{\Box}$ can be mounted close together.



Rectangular slit mask

• OS-CX-□×6 Fitted on the front face of the sensor with onetouch.

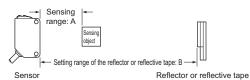
Rectangular slit mask





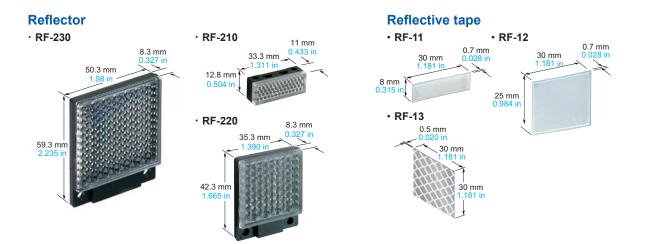
OPTIONS

Designation	Mode	l No.	Sensing range: A	Setting range of the reflector or reflective	Min. sensing	Description	
Designation		Sensor	(Note 2)	tape: B	object	Becomption	
		CX-491□	3 m 9.843 ft	0.1 to 3 m 0.328 to 9.843 ft		· Dimensions:	
		CX-493□	5 m 16.404 ft	0.1 to 5 m 0.328 to 16.404 ft		W50.3 × H59.3 × D8.3 mm W1.98 × H2.235 × D0.327 in	
	RF-230	CX-481□	50 to 500 mm 1.969 to 19.685 in	100 to 500 mm 3.937 to 19.685 in	ø50 mm ø1.969 in	· Mounting hole: ø4.6 mm ø0.181 in	
	CX-48		0.1 to 2 m 0.328 to 6.562 ft	0.8 to 2 m 2.625 to 6.562 ft		 Attached to the retroreflective type sensor except the type 	
			0.05 to 1 m 0.164 to 3.281 ft	.05 to 1 m 0.164 to 3.281 ft 0.1 to 1 m 0.328 to 3.281 ft		without reflector.	
Reflector		CX-491□	1 m 3.281 ft	0.1 to 1 m 0.328 to 3.281 ft	ø30 mm ø1.181 in		
(Note 1)		CX-493□	1.5 m 4.921 ft	0.1 to 1.5 m 0.328 to 4.921 ft	Ø30 IIIII Ø1. Ið I III	· Dimensions:	
For retroreflective	RF-210	CX-481□	—	—		W33.3 × H12.8 × D11 mm W1.311 × H0.504 × D0.433 in	
type sensor only		CX-482□	0.1 to 0.6 m 0.328 to 1.969 ft	0.3 to 0.6 m 0.984 to 1.969 ft	ø30 mm ø1.181 in	· Mounting hole: ø3.4 mm ø0.134 in	
		CX-483□	0.1 to 0.3 m 0.328 to 0.984 ft	0.1 to 0.3 m 0.328 to 0.984 ft	Ø30 MIN Ø1. IOT M		
		CX-491□	1.5 m <mark>4.921 ft</mark>	0.1 to 1.5 m 0.328 to 4.921 ft			
		CX-493□	3 m 9.843 ft	3 ft 0.1 to 3 m 0.328 to 9.843 ft		· Dimensions:	
	RF-220	CX-481□	50 to 300 mm 1.969 to 11.811 in	100 to 300 mm 3.937 to 11.811 in	ø35 mm ø1.378 in	W35.3 × H42.3 × D8.3 mm W1.390 × H1.665 × D0.327 in	
		CX-482□	0.1 to 1.3 m 0.328 to 4.265 ft	1.3 m 0.328 to 4.265 ft 0.5 to 1.3 m 1.64 to 4.265 ft		· Mounting hole: ø3.6 mm 0.142 in	
		CX-483□	0.1 to 0.7 m 0.328 to 2.297 ft	0.2 to 0.7 m 0.656 to 2.297 ft			
		CX-491□	0.5 m 1.640 ft	0.1 to 0.5 m 0.328 to 1.640 ft	ø30 mm ø1.181 in	· Dimensions: W30 × H8 × D0.7 mm	
		CX-493□	0.8 m 2.625 ft	0.1 to 0.8 m 0.328 to 2.625 ft	900 mm 91.101 m		
	RF-11 (Note 3)	CX-481□				W1.181 × H0.315 × D0.028 in · Ambient temperature:	
	(CX-482□				-25 to +50 °C -13 to +122 °F	
		CX-483□				Ambient humidity: 35 to 85% RH	
Reflective tape		CX-491□	0.7 m 2.297 ft	0.1 to 0.7 m 0.328 to 2.297 ft	ø30 mm ø1.181 in	· Dimensions:	
(Note 1)	Note 1) RF-12 CX-493□ For retroreflective (Note 3) CX-481□		1.2 m 3.937 ft	0.1 to 1.2 m 0.328 to 3.937 ft	900 mm 91.101 m	W30 × H25 × D0.7 mm	
For retroreflective			<u> </u>	<u> </u>		W1.181 × H0.984 × D0.028 in · Ambient temperature:	
type sensor only			0.1 to 0.6 m 0.328 to 1.969 ft	0.4 to 0.6 m 1.312 to 1.969 ft	ø30 mm ø1.181 in	-25 to +50 °C -13 to +122 °F	
			<u> </u>	<u> </u>		Ambient humidity: 35 to 85% RH	
		CX-491□	0.5 m 1.64 ft	0.2 to 0.5 m 0.656 to 1.64 ft	ø30 mm ø1.181 in	· Dimensions:	
		CX-493□	—			W30 × H30 × D0.5 mm	
	RF-13	CX-481□		<u> </u>		W1.181 × H1.181 × D0.020 in · Ambient temperature:	
		CX-482□		<u> </u>		-25 to +55 °C -13 to +131 °F	
	CX-4					Ambient humidity: 35 to 85% RH	



Notes 1) Be sure to align the beam axis when mounting the sensor and reflector or reflective tape. Use of the **RF-210** reflector or **RF-11** reflective tape requires more precise adjustment than when the **RF-230** reflector supplied with the product is used. Mount the reflector / reflective tape in such a way that the sensor angle can be adjusted in a wide range. For the sensor angle adjustment and reflector / reflective tape position adjustment, refer to "PRECAUTIONS FOR PROPER USE" on pages 20 and 21.
 2) Sensing range A may vary depending on the shape of the sensing object. Be sure to check the operation with the actual sensing object.

Sensing range A may vary depending on the shape of the sensing object. Be sure to check the operation with the actual sensing object.
 Do not press the reflective tape RF-11 and RF-12 strongly because they have soft surfaces. The internal prism may be crushed and the reflection distance may be reduced. Also, do not cut the tape before use. Performance will not be maintained.

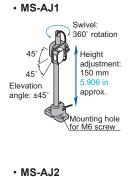


OPTIONS

Designation	Model No. Des		
Reflector	MS-RF21-1	Protective mounting bracket for RF-210 It protects the reflector from damage and	maintains alignment.
mounting bracket	MS-RF22	For RF-220	
	MS-RF23	For RF-230	
	MS-CX2-1	Foot angled mounting bracket It can also be used for mounting RF-210 .	
Sensor mounting	MS-CX2-2	Foot biangled mounting bracket It can also be used for mounting RF-210 .	The thru-beam type sensor needs two
bracket (Note)	MS-CX2-4	Protective mounting bracket	brackets.
	MS-CX2-5	Back biangled mounting bracket	
	MS-CX-3	Back angled mounting bracket	
	MS-AJ1	Horizontal mounting type	Basic assembly
	MS-AJ2	Vertical mounting type	Dasic assembly
Universal sensor mounting	MS-AJ1-A	Horizontal mounting type	Lateral arm assembly
stand	MS-AJ2-A	Vertical mounting type	Lateral ann assembly
	MS-AJ1-M	Horizontal mounting type	Assembly for reflector
	MS-AJ2-M	Vertical mounting type	

Note: The plug-in connector type sensor does not allow use of some sensor mounting brackets because of the protrusion of the connector.

Universal sensor mounting stand • MS-AJ1-A



Swivel:

6

Sp

45

45°

Elevation

angle: ±45

360° rotation

adjustment:

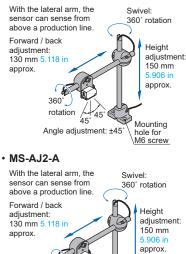
150 mm

006 ir

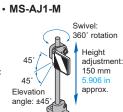
approx.

Mounting hole for M6 screw

Height

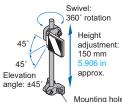


k 360 rotation Gi 45 45 Mounting Angle adjustment: ±45° hole for M6 screw



Mounting hole for M6 screw

MS-AJ2-M



Mounting hole for M6 screw

Reflector mounting bracket

• MS-RF21-1 MS-RF22





Two M3 (length 12 mm 0.472 in) screws with washers are attached

Two M3 (length 8 mm 0.315 in) screws with washers are attached.

• MS-RF23



Two M4 (length 10 mm 0.394 in) screws with washers are attached.

• MS-CX2-2

Sensor mounting bracket

• MS-CX2-1 Ø

• MS-CX2-4

Two M3 (length 12 mm

Two M3 (length 12 mm in) screws with washers are attached.



Two M3 (length 14 mm in) screws with washers are attached.

• MS-CX-3



Two M3 (length 12 mm 0.472 in) screws with washers are attached.



Two M3 (length 12 mm

0.472 in) screws with washers are attached.

0.472 in) screws with

Panasonic Industry Co., Ltd. | 11

SPECIFICATIONS

\bigwedge	Tupo		Thru-bean	ı		Re	etroreflect	ive		Diff	use reflec	tive		
	Туре		Long sens	sing range	With polarizing filters	Long sensing range	For trans	parent obje	ct sensing		use reliec	uve	Narrow-view	
	볼 NPN output	CX-411	CX-412	CX-413	CX-491	CX-493	CX-481	CX-483	CX-482	CX-424	CX-421	CX-421 CX-422 C		
Item \	PNP output	CX-411-P	CX-412-P	CX-413-P	CX-491-P	CX-493-P	CX-481-P	CX-483-P	CX-482-P	CX-424-P	CX-421-P	CX-422-P	CX-423-F	
	ble regulations ifications	CE Mark	ing (EMC D)irective, Ro	oHS Directi	ve), UKCA	Marking (El	MC Regulat	ions, RoHS	Regulatior	ns), UL Rec	ognition Ce	rtification	
Sensing	range	10 m 32.808 ft	15 m 49.213 ft	30 m 98.425 ft	3 m 9.843 ft (Note 2)	5 m 16.404 ft (Note 2)	50 to 500 mm 1.969 to 19.685 in (Note 2)	50 to 1,000mm 1.969 to 39.37 in (Note 2)	0.1 to 2 m 0.328 to 6.562 ft (Note 2)	100 mm 3.937 in (Note 3)	300 mm 11.811 in (Note 3)	800 mm 31.496 in (Note 3)	70 to 300 mm 2.756 to 11.811 in (Note	
Sensing	object	ø12 mm ø or more o	0.472 in paque objec	ct (Note 4)	ø50 mm ø1.969 in or more opaque, translucent or specular object (Note 2, 5)	ø50 mm ø1.969 in or more opaque or translucent object (Note 2, 5)	transpar	ent, translu object (Not	cent or		e, transluce irent object		Opaque, translucen or transparent object (Note 5) / Nn. sening object ø0.5 m ø0.020 n copper wire	
Hysteres	sis									15 % or le	ess of opera	tion distand	ce (Note 3)	
Repeatability ((perpendicular to sensing axis)			(0.5 mm 0.0	20 in or les	s			1 mn	n 0.039 in o	r less	0.5 mm 0.020 in or les	
Supply \	voltage					12 to 24 V [DC ±10 %	Ripple P-P	10 % or les	s				
Current	consumption	Receiver:	Emitter: 20 mA or less Receiver: 10 mA or less	Receiver:	or less		10 mA	or less		13 mA	or less	15 mA	or less	
Output		NPN 0 • N • A	output type> open-collect faximum sin pplied voltag Residual vol	or transisto nk current: ge: 30 V DC tage: 2 V or	100 mA or less (betw r less (at 10		current)	PN	 Applied vo 	ector transis source cur ltage: 30 V E voltage: 2 V	stor rent: 100 m OC or less (b or less (at 1 or less (at 1	etween outp 00 mA soure	ce current)	
Out	tput operation					Switcha	ble either L	ight-ON or	Dark-ON					
Sho	rt-circuit protection						Incorp	orated						
Respons	se time	1 ms	or less	2 ms or less					1 ms or less	3				
Operatio	on indicator		Or	ange LED (lights up w	hen the out	tput is ON)(incorporate	d on the red	eiver for th	ru-beam typ	pe)		
Stability	indicator	Green LE	D (lights up	under stat	ole light rec	eived condi	ition or stab	le dark con	dition)(inco	porated on	the receive	er for thru-b	eam type)	
Power ir	ndicator		(lights up whe rporated on the											
Sensitiv	ity adjuster			Contin	uously var	iable adjus	ter (incorpo	rated on the	e receiver fo	or thru-bear	n type)			
	tic interference on function	Two units of sensors can be mounted close together with interference prevention filters. (Sensing range: 5 m 16.404 ft)				Incor	porated (Tw	o units of s	ensors can	be mounte	d close toge	ether.)		
	tection						IP67	(IEC)						
mA istance	bient temperature		-25 to +5	5 °C -13 to	+131 °F (N	lo dew con	densation o	r icing allov	ved), Storaç	ge: -30 to +	70 °C - <mark>22</mark> to	+158 °F		
Am Sist	bient humidity					35 to 85	% RH, Sto	rage: 35 to	85 % RH					
Am a	bient illuminance				Inca	andescent li	ight: 3,000 {	x at the ligh	nt-receiving	face				
Volta Volta Vibi	age withstandability	1,000 V AC for one min. between all supply terminals connected together and enclosure												
Insu	ulation resistance	ance 20 MΩ, or more, with 250 V DC megger between all supply terminals connected together and enclos					closure							
Vibi	ration resistance	10 to 500 Hz frequency, 1.5 mm 0.059 in double amplitude (10 G max.) in X, Y and Z directions for two hours ex						hours eac	h					
_	ock resistance	500 m/s ² acceleration (50 G approx.) in X, Y and Z directions three times each												
Emitting e	element (modulated)	Red LED	Infrare	d LED	Red	LED	I	nfrared LEI	C	I	nfrared LE)	Red LED	
Peal	k emission wavelength							645 nm 0.025 m						
Material		Enclosure: PBT (Polybutylene terephthalate), Lens: Acrylic (CX-48:: Polycarbonate), Indicator cover: Acrylic (CX-48:: Polycarbonate)						carbonate)						
Cable		0.2 mm ² 3-core (thru-beam type emitter: 2-core) cabtyre cable, 2 m 6.562 ft long												
Cable e	xtension	E	tension up	to total 100	m 328.084 1	ft is possible	e with 0.3 mr	m ² , or more,	cable (thru-	beam type:	both emitter	and receiv	er)	
	Net	Enniner. 45 g a	appiox., Receive	i. ou y appilox.	Weight Gross 100 g approx. 80 g approx. 60 g approx.				ou g approx					

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were an ambient temperature of +23 °C +73.4 °F. 2) The sensing range and the sensing object of the retroreflective type sensor are specified for the **RF-230** reflector. The sensing range represents the actual sensing range of the sensor. The sensing range: A of the table below may vary depending on the shape of sensing object. Be sure to check the operation with the actual sensing object.

	ensing nge: A		CX-491□	CX-493□	CX-481□	CX-483□	CX-482□
	Sensing object	А	0 to 3 m 0 to 9.843 ft	0 to 5 m 0 to 16.404 ft	50 to 500 mm 1.969 to 19.685 in	50 to 1,000 mm 1.969 to 39.37 in	0.1 to 2 m 0.328 to 6.562 ft
	Setting range of the reflector: B	В	0.1 to 3 m 0.328 to 9.843 ft	0.1 to 5 m 0.328 to 16.404 ft	100 to 500 mm 3.937 to 19.685 in	100 to 1,000 mm 3.937 to 39.37 in	0.8 to 2 m 2.625 to 6.562 ft
Sensor	Reflector						

3) The sensing range and hysteresis of the diffuse reflective type sensor are specified for white non-glossy paper (200 × 200 mm 7.874 × 7.874 in) as the object.
4) If slit masks (optional) are fitted, an object of Ø0.5 mm Ø0.020 in (using round slit mask) can be detected.
5) Make sure to confirm detection with an actual sensor before use.

\mathbb{N}			Adjustable range reflective					
	Туре	Small spot						
	n $\frac{2}{9}$ NPN output PNP output	CX-441	CX-444	CX-442				
Iten	$n \bigvee_{\underline{S}} \overset{\underline{W}}{\underline{S}} PNP output$	CX-441-P	CX-444-P	CX-442-P				
	licable regulations and fications	CE Marking (EMC Directive, UL Recognition Certification	RoHS Directive), UKCA Marking (EMC Reg	ulations, RoHS Regulations),				
Adju	stable range (Note 2)	20 to 50 mm 0.787 to 1.969 in 20 to 100 mm 0.787 to 3.937 in 40 to 300 mm 1.575 to 11.811 i						
	sing range n white non-glossy paper)	2 to 50 mm 0.079 to 1.969 in	2 to 50 mm 0.079 to 1.969 in (Distance setting: 50 mm 1.969 in) 15 to 100 mm 0.591 to 3.937 in (Distance setting: 100 mm 3.937 in)	20 to 300 mm 0.787 to 11.811 in				
	eresis n white non-glossy paper)	2 % or less of op	peration distance	5 % or less of operation distance				
Rep	eatability	Along sensing axis: 1 mm 0.039 in or less	, Perpendicular to sensing axis: 0.2 mm 0.0	08 in or less (with white non-glossy paper)				
Sup	ply voltage	1.	2 to 24 V DC ±10 % Ripple P-P 10 % or les	SS				
Curr	ent consumption		20 mA or less					
Outp	put	<npn output="" type=""> NPN open-collector transistor • Maximum sink current: 100 mA • Applied voltage: 30 V DC or less (betw • Residual voltage: 2 V or less (at 100 1 V or less (at 16</npn>	een output and 0 V) • Applied volta 0 mA sink current) • Residual vol					
	Output operation	Sw	itchable either Detection-ON or Detection-C)FF				
	Short-circuit protection		Incorporated					
Res	ponse time		1 ms or less					
Ope	ration indicator	c	Prange LED (lights up when the output is ON	1)				
Stab	ility indicator	Green LEI	D (lights up under stable operating condition	n) (Note 3)				
Dista	ance adjuster		Multirotation mechanical adjuster					
Sen	sing mode	BGS / FGS funct	tions Switchable with wiring of sensing mod	le selection input				
Automa	atic interference prevention function (Note 4)		Incorporated					
	Protection		IP67 (IEC)					
nce	Ambient temperature	-25 to +55 °C -13 to +131 °F (No	o dew condensation or icing allowed), Stora	ge: -30 to +70 °C -22 to +158 °F				
vironmental resistance	Ambient humidity		35 to 85 % RH, Storage: 35 to 85 % RH					
al re	Ambient illuminance	Incar	ndescent light: 3,000 {x at the light-receiving	face				
nent	Voltage withstandability	1,000 V AC for one mi	n. between all supply terminals connected t	ogether and enclosure				
/iron	Insulation resistance	20 MΩ, or more, with 250 V D	C megger between all supply terminals con	nected together and enclosure				
ED	Vibration resistance	10 to 500 Hz frequency, 3 mm 0.11	18 in double amplitude (20 G max.) in X, Y a	and Z directions for two hours each				
	Shock resistance 500 m/s ² acceleration (50 G approx.) in X, Y and Z directions three times each							
Emit	ting element	Red LED (Pe	eak emission wavelength: 650 nm 0.026 mil	, modulated)				
Spot	t diameter	ø2 mm ø0.079 in approx. (at 50 mm 1.969 in distance)	ø9 mm ø0.354 in approx. (at 100 mm 3.937 in distance)	□15 mm □0.591 in approx. (at 300 mm 11.811 in distance)				
Mate	erial	Enclosure: PBT (Polybutyle	ne terephthalate), Lens: Polycarbonate, Ind	licator cover: Polycarbonate				
Cab	le	0.	2 mm ² 4-core cabtyre cable, 2 m 6.562 ft lo	ng				
Cab	le extension	Extension up to to	tal 100 m 328.084 ft is possible with 0.3 mm	n², or more, cable.				
Wei	ght	Net	weight: 55 g approx., Gross weight: 65 g ap	prox.				
Note	: 1) Whore measurement a		the conditions used were an ambient terr	porature of +22 °C +72 4 °E				

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were an ambient temperature of +23 °C +73.4 °F. 2) The adjustable range stands for the maximum sensing range which can be set with the distance adjuster. The sensor can detect an object 2 mm 0.079 in [CX-444(-P): 15 mm 0.591 in, CX-442(-P): 20 mm 0.787 in], or more, away.

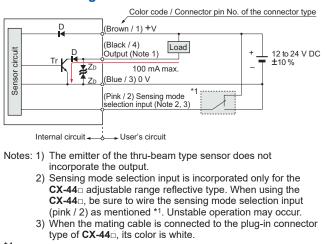


3) Refer to the "Stability indicator (p.23)" of "PRECAUTIONS FOR PROPER USE" for operation of the stability indicator.

4) Note that detection may be unstable depending on the mounting conditions or the sensing object. In the state that this product is mounted, be sure to check the operation with the actual sensing object.

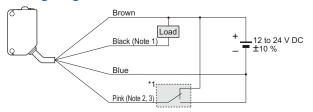
NPN output type

I/O circuit diagram



1	^-]
	 Sensing mode selection input
	BGS function: Connect to 0 V
	FGS function: Connect to +V

Wiring diagram



Notes: 1) The emitter of the thru-beam type sensor does not incorporate the black wire.
2) The pink wire is incorporated only for the CX-44

adjustable range reflective type. When using the CX-44

be sure to wire the pink wire as mentioned *1. Unstable operation may occur.

3) When the mating cable is connected to the plug-in connector

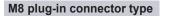
type of **CX-44**□, its color is white.

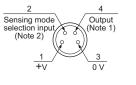
Sensing mode selection input

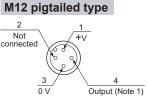
*1

BGS function: Connect to 0 V FGS function: Connect to +V

Connector pin position



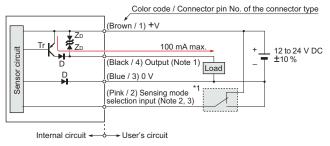




Notes: 1) The emitter of the thru-beam type sensor does not incorporate the output.
 2) Sensing mode selection input is incorporated only for the CX-44□ adjustable range reflective type. When using the CX-44□, be sure to wire the sensing mode selection input (pink / 2). Unstable operation may occur.

PNP output type

I/O circuit diagram



- Notes: 1) The emitter of the thru-beam type sensor does not incorporate the output.
 - 2) Sensing mode selection input is incorporated only for the CX-44□-P adjustable range reflective type. When using the CX-44□-P, be sure to wire the sensing mode selection input (pink / 2) as mentioned *1. Unstable operation may occur.
 - When the mating cable is connected to the plug-in connector type of CX-44
 -P, its color is white.

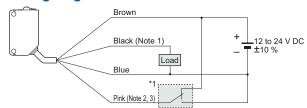
*1

 Sensing mode selection input BGS function: Connect to 0 V FGS function: Connect to +V

Symbols D : Reverse supply polarity protection diod	е
Z _D : Surge absorption zener diode	
Tr : PNP output transistor	

Wiring diagram

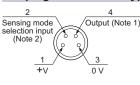
*1

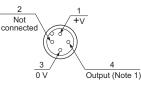


- Notes: 1) The emitter of the thru-beam type sensor does not incorporate the black wire.
 2) The pink wire is incorporated only for the CX-44
 --P adjustable range reflective type. When using the CX-44
 --P, be sure to wire the pink wire as mentioned *1. Unstable operation may occur.
 - 3) When the mating cable is connected to the plug-in connector type of CX-44 -- P, its color is white.
- Sensing mode selection input BGS function: Connect to 0 V FGS function: Connect to +V

Connector pin position

M8 plug-in connector type





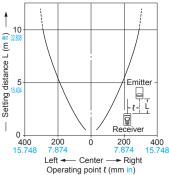
M12 pigtailed type

Notes: 1) The emitter of the thru-beam type sensor does not incorporate the output.
 2) Sensing mode selection input is incorporated only for the CX-44□-P adjustable range reflective type. When using the CX-44□-P, be sure to wire the sensing mode selection input (pink / 2). Unstable operation may occur.

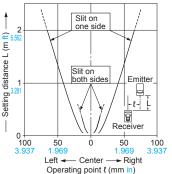
CX-411

Parallel deviation

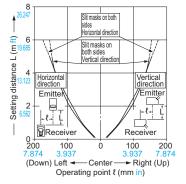


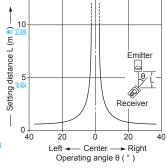


Parallel deviation with round slit masks (ø2 mm ø0.079 in)

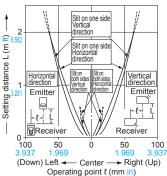


Parallel deviation with interference prevention filters (PF-CX4-V) on both sides

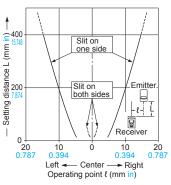




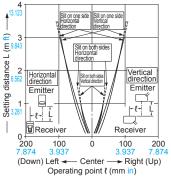
Parallel deviation with rectangular slit masks (0.5 × 6 mm 0.020 × 0.236 in)

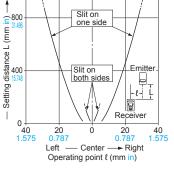


slit masks (ø0.5 mm ø0.020 in)



Parallel deviation with rectangular slit masks (1 × 6 mm 0.039 × 0.236 in)



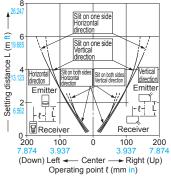


Parallel deviation with round

slit masks (ø1 mm ø0.039 in)

Thru-beam type

Parallel deviation with rectangular slit masks (2 × 6 mm 0.079 × 0.236 in)

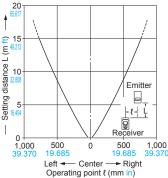


Parallel deviation with round

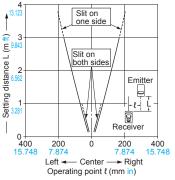
Please contact our office for the sensing characteristics of CX-413 and CX-483.

CX-412

Parallel deviation



Parallel deviation with round slit masks (ø2 mm ø0.079 in)



 $(\text{RF}\underline{\underline{-230}})$

-l- Ļ

Sensor

Center

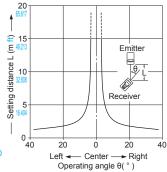
Operating point { (mm in)

100

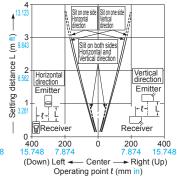
► Right

200 7.874

Angular deviation



Parallel deviation with rectangular slit masks (0.5 × 6 mm 0.020 × 0.236 in)



Retroreflective type

Reflector angular deviation

Sensor

angular deviation

Reflecto

angular deviation

Reflector (RF-230

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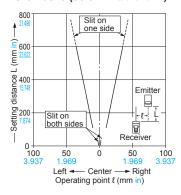
Sensor

Right

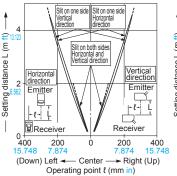
40

20

Parallel deviation with round slit masks (ø0.5 mm ø0.020 in)



Parallel deviation with rectangular slit masks (1 × 6 mm 0.039 × 0.236 in)

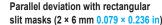


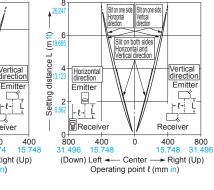
Slit on one side distance L (m ft) Emitter þ Setting 0.5 - 8-Slit on Receive both sides 31/ 0 200 100 100 0 200 7.87 3 93 Center Left ◄ - Right Operating point { (mm in)

Parallel deviation with round

slit masks (ø1 mm ø0.039 in)

Thru-beam type





CX-493□

r (m 👖 6

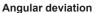
Setting distance

2

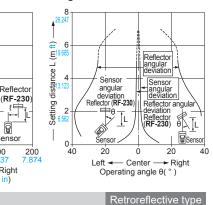
0 200

7.87

Parallel deviation



Retroreflective type



CX-481

CX-491□

13.123

3

2

28

0+ 200

7.87

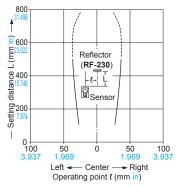
Setting distance L (m ft)

Parallel deviation

Parallel deviation

100

Left 🚽



Angular deviation

Angular deviation

Sensor angular deviation

Ô

20

Left

eflector (RF-230

PĻ

enso

Ó

Center

Operating angle θ (°)

Retroreflective type

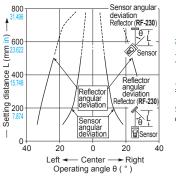
13.123

(**1** E 3

Setting distance L

2

0∔ 40





Parallel deviation

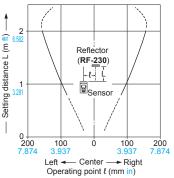
100

Left -

Ó

Center

Operating point { (mm in)



l ➡

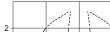
Sensor

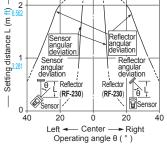
100

+ Right

3.93

Angular deviation

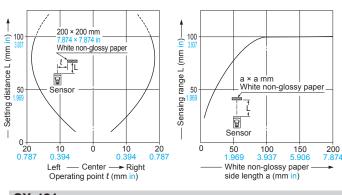




CX-424

Sensing field

Correlation between sensing object size and sensing range



As the sensing object size becomes smaller than the standard size (white non-glossy paper 200 × 200 mm 7.874 × 7.874 in), the sensing range shortens, as shown in the left graph. For plotting the left graph, the sensitivity has been set such that a 200 × 200 mm 7.874 × 7.874 in white non-glossy paper is just detectable at a distance of 100 mm 3.937 in.

CX-421□

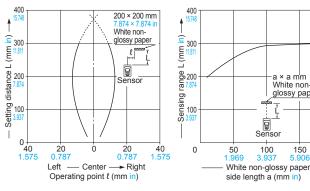
Sensing field

Correlation between sensing object size and sensing range

a × a mˈm

White nonglossy paper

150



As the sensing object size becomes smaller than the standard size (white non-glossy paper 200 × 200 mm 7.874×7.874 in), the sensing range shortens, as shown in the left graph.

For plotting the left graph, the sensitivity has been set such that a 200 × 200 mm 7.874 × 7.874 in white non-glossy paper is just detectable at a distance of 300 mm 11.811 in.

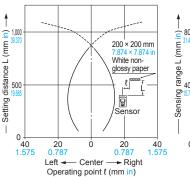
Diffuse reflective type

Diffuse reflective type

Diffuse reflective type

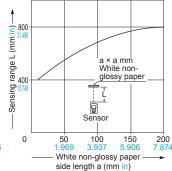
Sensing field

CX-422□



Correlation between sensing object size and sensing range

200 7.874

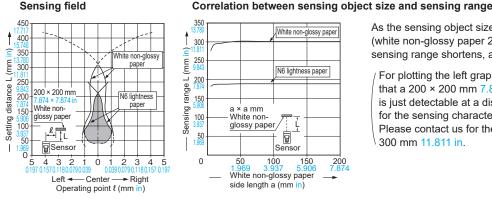


As the sensing object size becomes smaller than the standard size (white non-glossy paper 200 \times 200 mm 7.874 \times 7.874 in), the sensing range shortens, as shown in the left graph.

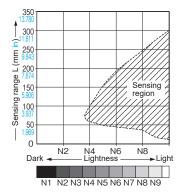
For plotting the left graph, the sensitivity has been set such that a 200 × 200 mm 7.874×7.874 in white non-glossy paper is just detectable at a distance of 800 mm 31.496 in.

CX-423

Sensing field



Correlation between lightness and sensing range



The sensing region is represented by oblique lines in the left figure. However, the sensitivity should be set with an enough margin because of slight variation in products.

a × a mm White non∙

50

glossy paper

N6 lightness paper

Ļ

150

200 7.874

6

Sensor

100

White non-glossy paper

side length a (mm in)

Lightness shown on the left may differ slightly from the actual object condition.

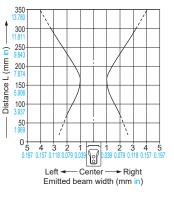
As the sensing object size becomes smaller than the standard size White non-glossy paper

(white non-glossy paper 200 \times 200 mm 7.874 \times 7.874 in), the sensing range shortens, as shown in the left graph. For plotting the left graph, the sensitivity has been set such

that a 200 × 200 mm 7.874 × 7.874 in white non-glossy paper is just detectable at a distance of 200 mm 7.874 in. Contact us for the sensing characteristics of 300 mm 11.811 in distance. Please contact us for the sensing field at the setting distance 300 mm 11.811 in.

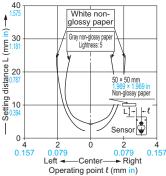
Emitted beam

Emitted beam



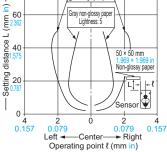
Sensing fields

• Setting distance: 25 mm 0.984 in



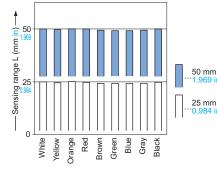
80 White nonglossy paper

Setting distance: 50 mm 1.969 in



Correlation between color

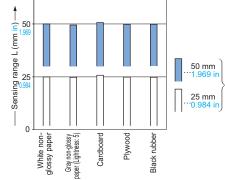
(50 × 50 mm 1.969 × 1.969 in construction paper) and sensing range



These bars indicate the sensing range with the respective colors when the distance adjuster is set to a sensing range of 50 mm 1.969 in and 25 mm 0.984 in long, respectively, with white

color. The sensing range also varies depending on material.

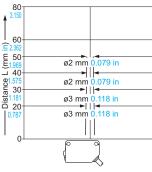
Correlation between material (50 × 50 mm 1.969 × 1.969 in) and sensing range



These bars indicate the sensing range with the respective objects when the distance adjuster is set to a sensing range of 50 mm 1.969 in and 25 mm 0.984 in long, respectively, with white non-glossy paper.



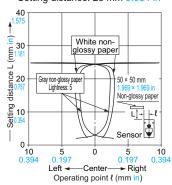
Diffuse reflective type

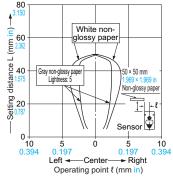


CX-444

Sensing fields

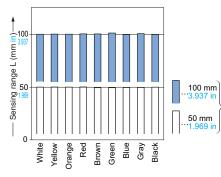
Setting distance: 25 mm 0.984 in



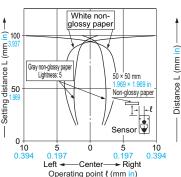


Setting distance: 50 mm 1.969 in

Correlation between color (50 × 50 mm 1.969 × 1.969 in construction paper) and sensing range



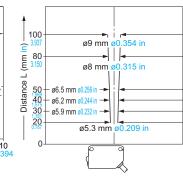
These bars indicate the sensing range with the respective colors when the distance adjuster is set to a sensing range of 100 mm 3.937 in and 50 mm 1.969 in long, respectively, with white color. The sensing range also varies depending on material.



• Setting distance: 100 mm 3.937 in

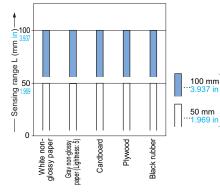
Emitted beam

Adjustable range reflective type



Correlation between material

(50 × 50 mm 1.969 × 1.969 in) and sensing range

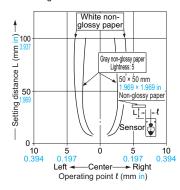


These bars indicate the sensing range with the respective objects when the distance adjuster is set to a sensing range of 100 mm 3.937 in and 50 mm 1.969 in long, respectively, with white non-glossy paper.

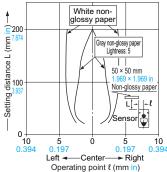
CX-442

Sensing fields

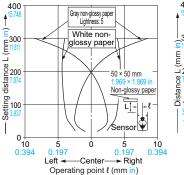
• Setting distance: 100 mm 3.937 in



• Setting distance: 200 mm 7.874 in



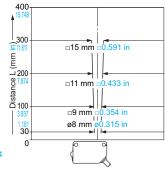
Setting distance: 300 mm 11.811 in



00-----

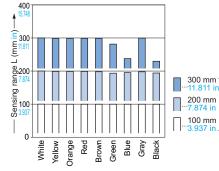
Emitted beam

Adjustable range reflective type



Correlation between color

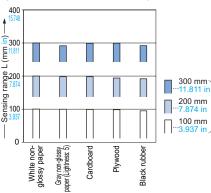
(50 × 50 mm 1.969 × 1.969 in construction paper) and sensing range



These bars indicate the sensing range with the respective colors when the distance adjuster is set to a sensing range of 300 mm 11.811 in, 200 mm 7.874 in and 100 mm 3.937 in long, respectively, with white color.

The sensing range also varies depending on material.

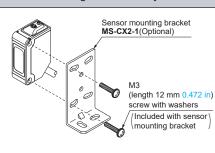
Correlation between material (50 × 50 mm 1.969 × 1.969 in) and sensing range



These bars indicate the sensing range with the respective objects when the distance adjuster is set to a sensing range of 300 mm 11.811 in, 200 mm 7.874 in and 100 mm 3.937 in long, respectively, with white non-glossy paper.

All models

- Never use this product as a sensing device for personnel protection.
- In case of using sensing devices for
- personnel protection, use products which meet laws and standards, such as OSHA, ANSI or IEC etc., for personnel protection applicable in each region or country.
- Mounting
- The tightening torque should be 0.5 N·m or less.



Wiring

- Make sure that the power supply is off while wiring.
- Take care that wrong wiring will damage the sensor.
- Verify that the supply voltage variation is within the rating.
- If power is supplied from a commercial switching regulator, ensure that the frame ground (F.G.) terminal of the power supply is connected to an actual ground.
- In case noise generating equipment (switching regulator, inverter motor, etc.) is used in the vicinity of this product, connect the frame ground (F.G.) terminal of the equipment to an actual ground.
- · Do not run the wires together with high-voltage lines or power lines or put them in the same raceway. This can cause malfunction due to induction.
- When connecting an inductive load such as a relay to the output, do not connect a capacitive load to prevent resonance. Also, connect a diode to protect the output circuit.
- Extension up to total 100 m 328.084 ft (thru-beam type: both emitter and receiver) is possible with 0.3 mm², or more, cable. However, in order to reduce noise, make the wiring as short as possible.
- Make sure that stress by forcible bend or pulling is not applied directly to the sensor cable joint.

Others

- · This product has been developed / produced for industrial use only.
- Do not use during the initial transient time (50 ms) after the power supply is switched on.
- · Take care that the sensor is not directly exposed to fluorescent light from a rapid-starter lamp or a high frequency lighting device, as it may affect the sensing performance.
- · This sensor is suitable for indoor use only.
- Do not use this sensor in places having excessive vapor, dust, etc., or where it may come in direct contact with water or corrosive gas.
- Take care that the sensor does not come in direct contact with water, oil, grease or organic solvents, such as, thinner. etc.
- This sensor cannot be used in an environment containing inflammable or explosive gases.
- · Never disassemble or modify the sensor.

CX-41 CX-42 CX-49 CX-48

Part description and functions

Stability indicator (Green) (Note 1) Lights up under the stable light condition or the stable dark condition

Operation indicator (Orange) (Note 2) Lights up when the sensing output is ON

Sensitivity adjuster (Note 1) Sensing range becomes longer when turned.

Operation mode switch (Note 1) L: Light-ON D: Dark-ON

Notes: 1) Not incorporated on the thru-beam type sensor emitter. 2) It is the power indicator (green, lights up when the power is ON.) for the thru-beam type sensor emitter.

Operation mode switch

Operation mode switch	Description
	Light-ON mode is obtained when the operation mode switch (thru-beam type in- corporate it in the receiver) is turned fully clockwise (L side).
	Dark-ON mode is obtained when the opera- tion mode switch (thru-beam type incorpo- rate it in the receiver) is turned fully counter- clockwise (D side).

Note: Use the flathead screwdriver (purchase separately) to turn the operation mode switch slowly.

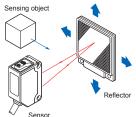
Beam alignment

Thru-beam type

- 1. Set the operation mode switch to the Light-ON mode position (L side).
- 2. Place the emitter and the receiver face to face along a straight line, move the emitter in the up, down, left and right directions, in order to determine the range of the light received condition with the help of the operation indicator (orange). Then, set the emitter at the center of this range.
- 3. Similarly, adjust for up, down, left and right angular movement of the emitter. Sensing object
- 4. Further, perform the angular adjustment for the receiver also.
- 5. Check that the stability indicator (green) lights up.
- 6. Choose the operation mode, Light-ON or Dark-ON, as per your requirement, with the operation mode switch

Retroreflective type

- Set the operation mode switch to the Light-ON mode position (L 1. side).
- 2. Placing the sensor and the reflector face to face along a straight line, move the reflector in the up, down, left and right directions, in order to determine the range of the light received condition with the help of the operation indicator (orange). Then, set the reflector at the center of this range.
- 3. Similarly, adjust for up, down, left and right angular movement of the reflector.
- 4. Further, perform the angular adjustment for the sensor also.
- Check that the stability indicator 5. (green) lights up.
- 6. Choose the operation mode, Light-ON or Dark-ON, as per your requirement, with the operation mode switch.

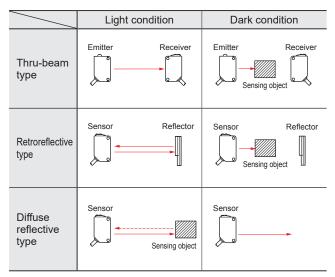


CX-410 CX-420 CX-490 CX-480

Sensitivity adjustment

Step	Sensitivity adjuster	Description	
1	MIN MAAX	Turn the sensitivity adjuster fully counterclockwise to the minimum sensitivity position, MIN.	
2	MIM MIN	In the light received condition, turn the sensitivity adjuster slowly clockwise and confirm the point (A) where the sensor enters the "Light" state operation.	
3	B MAAX MIN	In the dark condition, turn the sensitivity adjuster further clockwise until the sensor enters the "Light" state operation and then bring it back to confirm point (B) where the sensor just returns to the "Dark" state operation. (If the sensor does not enter the "Light" state operation even when the sensitivity adjuster is turned fully clockwise, the position is point (B).	
4	Optimum position (A) (B) (B) (B) (B) (C) (C) (C) (C) (C) (C) (C) (C) (C) (C	The position at the middle of points $$ and $$ is the optimum sensing position.	

Note: Use the flathead screwdriver (purchase separately) to turn the adjuster slowly. Turning with excessive strength will cause damage to the adjuster.

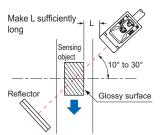


Relation between output and indicators

In ca	In case of Light-ON			In ca	se of Dar	k-ON
Stability indicator	Operation indicator	Output	Sensing condition	Output	Operation indicator	Stability indicator
•	-	ON	Stable light receiving			•
			Unstable light receiving	OFF	•	
•	•	OFF	Unstable dark receiving	ON		
•			Stable dark receiving			•
●, ●: Lights up, ●: Turns OFF						

Retroreflective type sensor (excluding CX-491)

- Please take care of the following points when detecting materials having a gloss.
- ① Make L, shown in the diagram, sufficiently long.
- ② Install at an angle of 10 to 30 degrees to the sensing object.



Retroreflective type sensor with polarizing filters (CX-491 \square)

• If a shiny object is covered or wrapped with a transparent film, such as those described below, the retroreflective type sensor with polarizing filters may not be able to detect it. In that case, follow the steps given below.

Example of sensing objects

- · Can wrapped by clear film
- Aluminum sheet covered by plastic film
- Gold or silver color (specular) label or wrapping paper

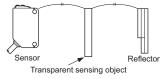
Steps

- Tilt the sensor with respect to the sensing object while fitting.
- · Reduce the sensitivity.
- Increase the distance between the sensor and the sensing object.

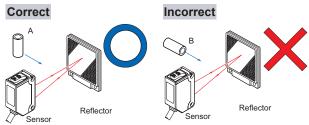
CX-48□

Retroreflective type sensor for transparent object sensing (CX-48)

• Optimum sensing is possible when the position of the transparent sensing object is set at the center of the sensor and the reflector. If the sensing position is set near the sensor or the reflector, the sensing may be unstable. In this case, set the sensing position at the center of the sensor and the reflector.



- When the sensor detects an uneven plastic receptacle or glass bottle, the received-light amount may differ with the sensing position or direction. Adjust the sensitivity after confirming the stable sensing condition by turning the sensing object, etc.
- When sensing pipe-shaped transparent sensing object, set it in a standing, not lying, position as shown in Figure A. The sensor may fail to detect a lying object as shown in Figure B.



PRECAUTIONS FOR PROPER USE

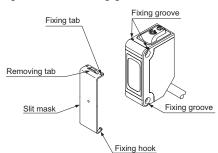
CX-41□

Slit mask (Optional)

• With the slit mask **OS-CX-**□, the sensor can detect a small object. However, the sensing range is reduced when the slit mask is mounted.

How to mount

- 1. Insert the fixing hook into the fixing groove.
- 2. Then, pressing the slit mask against the main unit, insert the fixing tab into the fixing groove.



How to remove

- 1. Insert a screwdriver into the removing tab.
- 2. Pull forward while lifting the removing tab.

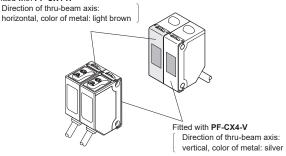
Interference prevention filter (Optional) (only for CX-411)

- By mounting the interference prevention filters (PF-CX4-H, PF-CX4-V), two sets of the CX-411
 can be mounted close together.
- The filters can be mounted and removed in the same way as for the above slit.

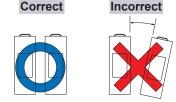
(Precaution for use)

- PF-CX4-H and PF-CX4-V are polarizing filters that allow only vertical light waves and horizontal light waves to pass through, respectively. Take note of the following when using.
 - The detection distance becomes shorter when the sensor units are mounted with the interference prevention filters.
 - There are two types of interference prevention filter. The emitter and receiver of each unit must be installed with different filter types.
 - The interference prevention function does not work if only the emitters or only the receivers are mounted with the filters or if both sensor units are mounted with the same type of filters.

Fitted with PF-CX4-H



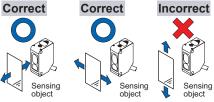
- * Interference prevention filters have no model indications. Check the filters carefully when mounting on sensors.
- If two sensor units mounted with the interference prevention filters are installed in tilted positions, the detection distance and interference area may become affected. Be sure to mount both units horizontally.



CX-44□

Mounting

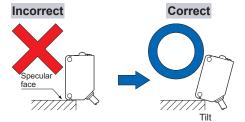
• Care must be taken regarding the sensor mounting direction with respect to the object's direction of movement.



The instruction

Do not make the sensor detect an object in this direction because it may cause unstable operation.

- When detecting a specular object (aluminum or copper foil, etc.) or an object having a glossy surface or coating, please take care that there are cases when the object may not be detected due to a change in angle, wrinkles on the object surface, etc.
- When a specular body is present below the sensor, use the sensor by tilting it slightly upwards to avoid wrong operation.

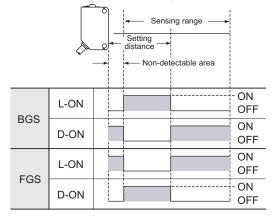


- If a specular body is present in the background, wrong operation may be caused due to a small change in the angle of the background body. In that case, install the sensor at an inclination and confirm the operation with the actual sensing object.
- Take care that there is a non-detectable area right in front of the sensor.

Operation mode switch

Operation mode switch	Description
	Detecting-ON mode is obtained when the operation mode switch is turned fully clockwise (L side).
	Not detecting-ON is obtained when the operation mode switch is turned fully counterclockwise (D side)

- Note: Use the flathead screwdriver (purchase separately) to turn the operation mode switch slowly. Turning with excessive strength will cause damage to the adjuster.
- Depending on whether you select the BGS or FGS function, the output operation changes as follows.

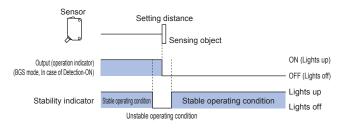


CX-44□

Stability indicator

 Since the CX-44
 use a 2-segment photodiode as its receiving element, and sensing is done based on the difference in the incident beam angle of the reflected beam from the sensing object, the output and the operation indicator (orange) operate according to the object distance.

Further, the stability indicator (green) shows the margin to the setting distance.

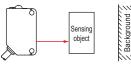


BGS/FGS functions

 This sensor incorporates BGS/FGS functions. Select either BGS or FGS function depending on the positions of the background and sensing object.

BGS function

• This function is used when the sensing object is apart from the background.

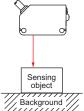


FGS function

• This function is used when the sensing object contacts the background or the sensing object is glossy, etc.

Please use the FGS function together

with a conveyor or other background



Distance adjustment

• When this product is used, be sure to carry out the distance adjustment.



unit.

- Since the distance adjuster of this sensor is a multirotation adjuster, when the point (A) and (B) is adjusted as explained in the table right, there may be more than 1 turn between the point (A) and (B). Therefore, make sure to remember the turns of both points to find the optimum position.
- Be sure to wire the sensing mode selection input (Pink / 2) before distance adjustment. If the wiring is done after the distance adjustment, the sensing area is changed.
- Turn the distance adjuster gradually and lightly with a flathead screwdriver (purchase separately). In order to protect itself, the distance adjuster idles if turned fully. If the adjuster is idled when distance adjustment is done, carry out the adjustment again.

When using the BGS function

<When a sensing object is moving right or left to the sensor>

Step	Description	Distance adjuster
1	Turn the distance adjuster fully counterclockwise to the minimum sensing range position. (CX-441□/444□: 20 mm 0.787 in approx., CX-442□: 40 mm 1.575 in approx.)	
2	Place an object at the required distance from the sensor, turn the distance adjuster gradually clockwise, and find out point (A) where the sensor changes to the detecting condition.	NEAR FAR
3	Remove the object, turn the adjuster clockwise further until the sensor goes into the detecting state again. Once it has entered, turn the distance adjuster backward until the sensor returns to the non-detecting condition. This position is designated as point (B). When the sensor does not go into the detecting condition even if the adjuster is turned fully clockwise, the position where the adjuster was fully turned is regarded as the point (B). (There may be more than 1 turn between point (A) and (B), since this sensor incorporates a multirotation adjuster.	NEAR NEAR
4	The optimum position to stably detect objects is the center point between (A) and (B).	A Optimum position B FAR

<When a sensing object is approaching / moving away from the sensor>

• Follow only steps ① and ②. Since the sensing point may change depending on the sensing object, be sure to check the operation with the actual sensing object.

When using the FGS function

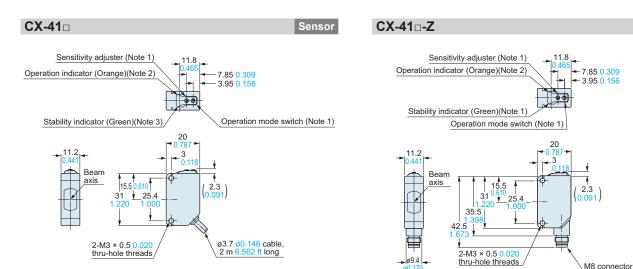
· Please use the FGS function together with a conveyor or other background unit.

		Distance
Step	Description	adjuster
1	Turn the distance adjuster fully clockwise to the maximum sensing range position. (CX-441□: 50 mm 1.969 in approx., CX-444□: 100 mm 3.937 in approx., CX-442□: 300 mm 11.811 in approx.)	NEAR FAR
2	In the state where the sensor detects the background, turn the distance adjuster gradually counterclockwise, and find out point (A) where the sensor changes to the non-detecting condition.	NEAR FAR
3	Place an object at the required distance from the sensor, turn the adjuster counterclockwise further until the sensor goes into the non- detecting condition again. Once entered, turn the distance adjuster backward until the sensor returns to the detecting condition. This position is designated as point (B). When the sensor does not go into the non-detecting condition even if the adjuster is turned fully counterclockwise, the position where the adjuster was fully turned is regarded as the point (B). (There may be more than 1 turn between point (A) and (B), since this sensor incorporates a multirotation adjuster.	B NEXT FAI
4	The optimum position to stably detect objects is the center point between (A) and (B).	Optimum A position B NEAR FAI

Others

• Its distance adjuster is mechanically operated. Do not drop; avoid other shocks.

Sensor



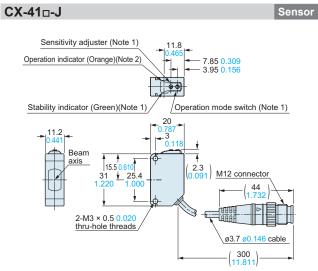
Notes: 1) Not incorporated on the emitter.

2) It is the power indicator (green) on the emitter.

Not incorporated on the emitter.

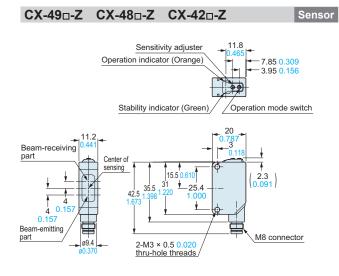
Notes: 1) Not incorporated on the emitter.

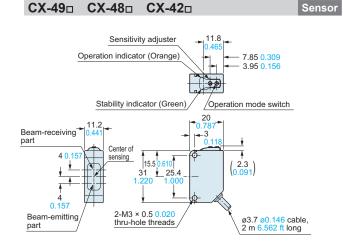
2) It is the power indicator (green) on the emitter.

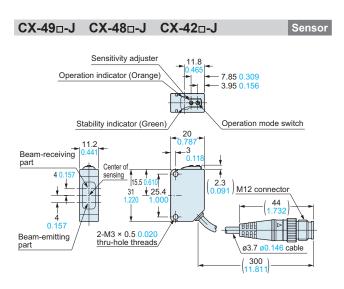


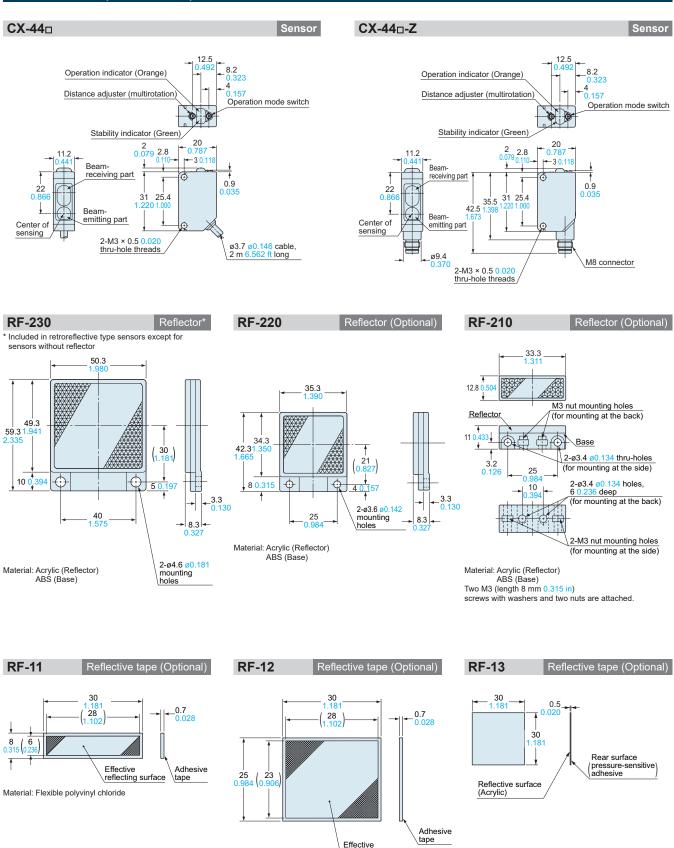
Notes: 1) Not incorporated on the emitter.

2) It is the power indicator (green) on the emitter.







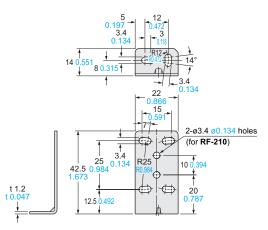


Material: Flexible polyvinyl chloride

reflecting surface

Sensor mounting bracket (Optional)

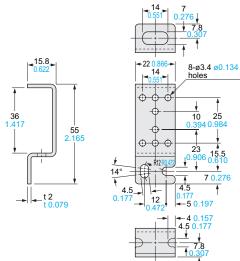
MS-CX2-1



Material: Stainless steel (SUS304)

Two M3 (length 12 mm 0.472 in) screws with washers are attached.

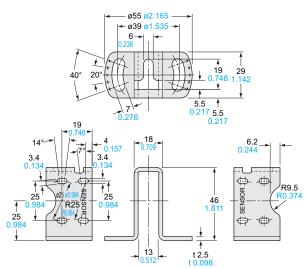
MS-CX2-2



Material: Stainless steel (SUS304)

Two M3 (length 12 mm 0.472 in) screws with washers are attached.

MS-CX2-4

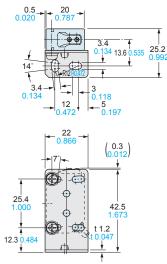


Material: Stainless steel (SUS304)

Two M3 (length 14 mm 0.551 in) screws with washers are attached.

Assembly dimensions

Mounting drawing with the receiver of **CX-41**□



Sensor mounting bracket (Optional)

Assembly dimensions

Beam axis

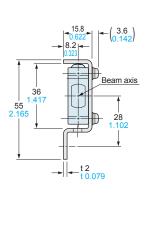
Mounting drawing with the receiver of **CX-41**

31

9.5

0.37

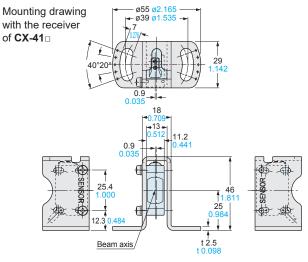
25



4 0.157 ¢ 6 -0 0 25.4 ф ی و ک 15.5 1 7 0.276 1 .5 45 4 0.1 12 5 0.197 4 0.157 4.5 0. 8.2 0.323

Sensor mounting bracket (Optional)

Assembly dimensions



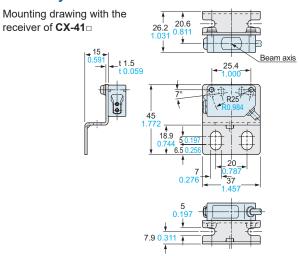
15

0 591

MS-CX2-5

Sensor mounting bracket (Optional)

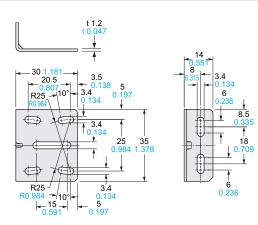
Assembly dimensions



Material: Stainless steel (SUS304)

Two M3 (length 12 mm 0.472 in) screws with washers are attached.

MS-CX-3



25 0.984 19 0.748 19

-R19

Ŕ25

20

7 0.78 276 37

8

3.4

0.1 3.4

3.5

18.9 0.744 6.5 0.256

0

.

7.9

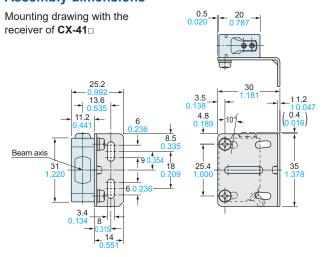
t 1.5 t 0.059

> 45 1.77

Material: Stainless steel (SUS304)

Two M3 (length 12 mm 0.472 in) screws with washers are attached.

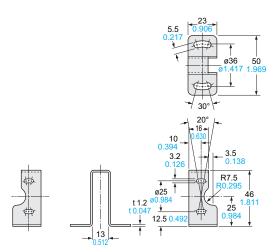
Assembly dimensions



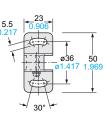
Sensor mounting bracket (Optional)

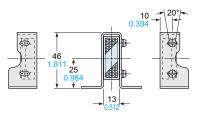
Reflector mounting bracket for **RF-210** (Optional)

MS-RF21-1



Assembly dimensions

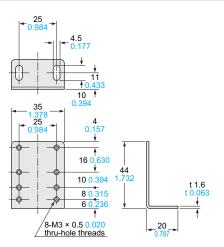




Material: Stainless steel (SUS304)

Two M3 (length 12 mm 0.472 in) screws with washers are attached.

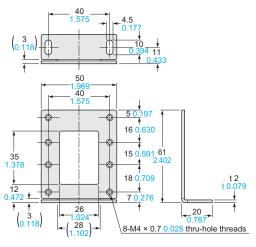
MS-RF22



Material: Cold rolled carbon steel (SPCC) (Uni-chrome plated)

Two M3 (length 8 mm 0.315 in) screws with washers are attached.

MS-RF23

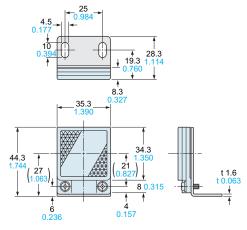


Material: Cold rolled carbon steel (SPCC) (Uni-chrome plated)

Two M4 (length 10 mm 0.394 in) screws with washers are attached.

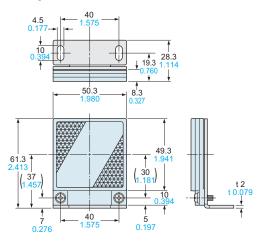
Reflector mounting bracket for **RF-220** (Optional)



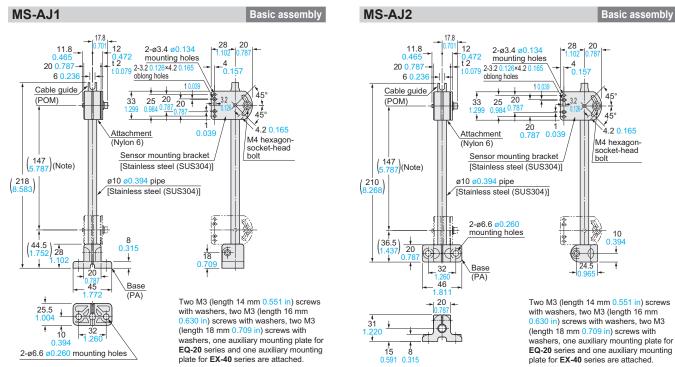


Reflector mounting bracket for **RF-230** (Optional)

Assembly dimensions



The CAD data can be downloaded from our website.



Note: The dimensions in the brackets indicate the adjustable range of the movable part.

Basic assembly

Basic assembly

ł

45°

bolt

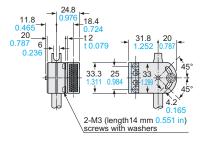
4.2 0.165

M4 hexagon-socket-head

10

0.

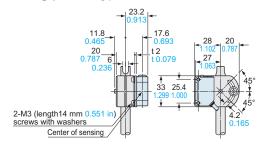
Assembly dimensions with RF-210 (Reflector) (Mounting part only)



Note: The dimensions in the brackets indicate the adjustable range of the movable part.

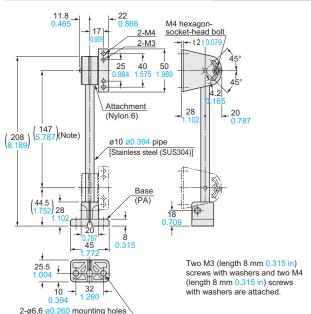
MS-AJ1 MS-AJ2

Assembly dimensions with CX-400 series (Mounting part only)



The CAD data can be downloaded from our website.

MS-AJ1-M

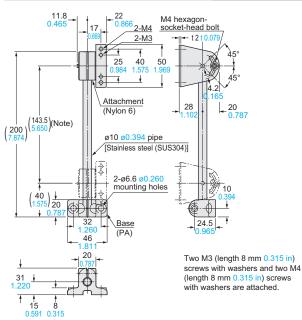


Note: The dimensions in the brackets indicate the adjustable range of the movable part.

MS-AJ2-M

Assembly for reflector

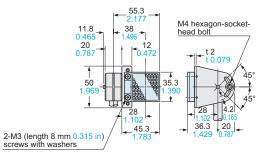
Assembly for reflector



Note: The dimensions in the brackets indicate the adjustable range of the movable part.

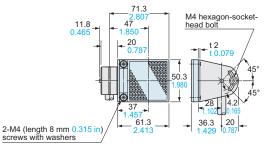
MS-AJ1-M MS-AJ2-M

Assembly dimensions with RF-220 (Reflector) (Mounting part only)



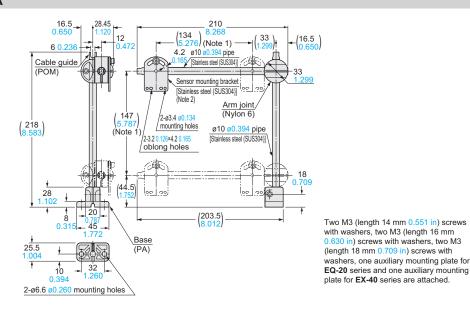
Assembly for reflector

Assembly dimensions with RF-230 (Reflector) (Mounting part only)

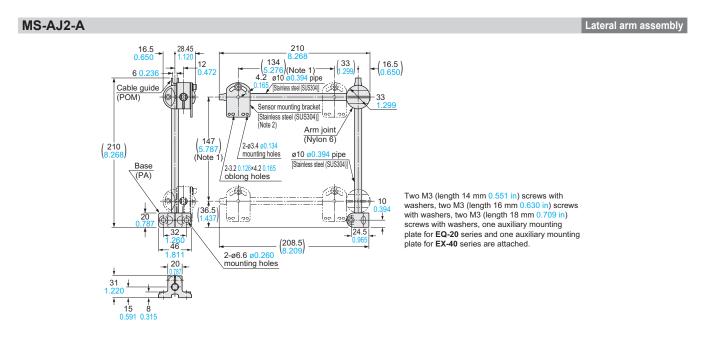


Lateral arm assembly

MS-AJ1-A



Notes: 1) The dimensions in the brackets indicate the adjustable range of the movable part. 2) Refer to **MS-AJ1** / **MS-AJ2** for the assembly dimensions with the sensor mounting bracket, sensor or reflector.



Notes: 1) The dimensions in the brackets indicate the adjustable range of the movable part. 2) Refer to **MS-AJ1** / **MS-AJ2** for the assembly dimensions with the sensor mounting bracket, sensor or reflector.

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